





Università degli Studi di Napoli Federico II PhD program in Information Technology and Electrical Engineering

PhD Student: Angela Marino

Cycle: XXXV

Training and Research Activities Report

Academic year: 2020-21 - PhD Year: Second

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Tutor: prof. Augusto Aubry

Co-Tutor: Dr Paolo Braca

Date: October 21, 2021

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PhD student: Cycle: XXXV

1. Information:

➤ PhD student: Angela Marino PhD Cycle: XXXV

> DR number: 993888

> Date of birth: 07/06/1995

> Master Science degree: Telecommunication Engineering University: University of Naples

"Federico II"

> Scholarship type: funded by NATO Science and Technology Organization - Centre for

Maritime Research and Experimentation

> Tutor: Prof. Augusto Aubry

> Co-tutor: Dr. Paolo Braca

2. Study and training activities:

Activity	Type ¹	Hours	Credits	Dates	Organizer	Certificate ²
	Semina	1	0.2	27/11/202	Rachel	N
"Patent Searching Best	r			0	Berrington	
Practices with IEEE						
Xplore"						
"How to Get Published	Semina	1	0.2	02/12/202	Rachel	N
with the IEEE"	r			0	Berrington	
"Subclonal	Semina	1.5	0.3	11/12/202	Prof.	Y
reconstruction of tumor	r			0	Michele	
architectures by using					Ceccarelli	
machine learning and population genetics"						
population genetics						
1st International Virtual	Semina	10	2	22/12/20 -	University	Y
School on Radar Signal	r	_ *	_	23/12/20	of	_
Processing (10 hours of					Electronic	
lectures)					Science and	
·					Technology	
					of China	
					(UESTC)	
Submission of the	Researc		6	01/11/202		
summary of the study	h			1 -		
"2D Constrained PBR				31/12/202		
Localization Via Active				1		
Radar Designation" at						
the student contest of						
The 1st International						
Virtual School on Radar						

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Signal Processing.						
Presentation of the						
contribution at the						
student contest of The						
1st International Virtual						
School on Radar Signal						
Processing: 3th						
classified.						
Performance assessment						
of the developed 3D						
localization techniques						
exploiting both active						
and passive sensing						
systems. MSc course –	Courses	72	9	29/09/202	Prof.	Y
Radiolocalizzazione	Courses	, <u>-</u>		0-	Augusto	_
Terrestre e Satellitare -				18/12/202	Aubry-	
				0	DIEŤI,	
					UniNA	
Advances in Machine	Semina	1	0.2	27/01/202	IEEE	N
Learning for Modelling	r			1	Geoscience	
and Understanding in					and Remote	
Earth Sciences – Gustau					Sensing	
Camps-Valls					South Italy	
Finalization of the	Researc		7	01/01/202	Chapter	
research activity	h Researc		/	1 -		
regarding localization	11			29/02/202		
techniques for				1		
multiplatform radar				1		
systems with deployable						
nodes.						
Robo Ludens: A game	Semina	1	0.2	05/03/202	Prof. Silvia	Y
design taxonomy for	r			1	Rossi-	
human-robot interaction,					DIETI,	
Dr. John Edison Muñoz					UniNA	
Cardona						
Dai mainframe all'IoT:	Semina	2	0.4	08/03/202	Prof.	N
una retrospettiva	r	_	3.1	1	Alessando	_ 1
sull'evoluzione delle					Cilardo	
architetture di calcolo -					(DIETI,	
prof. Antonino Mazzeo					UniNA)	
	g .	1	0.2	00/02/202	A . D . C	3 . 7
Electrical and Computer	Semina	1	0.2	09/03/202	Asst. Prof.	N
Engineering (ECE) Seminar:	r			1	Shiva Abbaszade	
SCIIIIIai.					h Abbaszade	
			1		11	

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					·	,
Towards Neural Signal						
Processing and Imaging-						
Dr. Gordon Wetzstein						
Electrical and Computer	Semina	1	0.2	15/03/202	Dr.	N
Engineering (ECE)	r			1	Shuping	
Seminar:					Dang	
6G: A New Frontier for						
the Design of NOMA-						
Prof. Zhiguo Ding						
Antonio Picariello	Semina	1	1.5	02/03/202	Prof. Flora	Y
Lectures on Data	r	1	1.5	1-	Amato	1
Science (Lecture 5-14-	1			03/03/202	(DIETI,	
15-16-17): "At the				1-	UniNA)	
Nexus of Big Data,				10/03/202	Prof.	
Machine Intelligence,				1-	Giuseppe	
and Human Cognition",				17/03/202	Longo	
"Visual Interaction and				1-	(Fisica	
Communication in Data				25/03/202	"Ettore	
Science", "Big Data and				1	Pancini" -	
Computational					UniNA)	
Linguistics", "Sensoria						
Health", "The coming						
revolution of Data driven						
Discovery"						
Cooperative and Non	Course	12	3	22/03/202	Profs.	Y
Cooperative	Course	12		1 -	Augusto	•
Localization Systems-				09/04/202	Aubry,	
Profs. Augusto Aubry,				1	Antonio De	
Antonio De Maio Dr.					Maio Dr.	
Vincenzo Carotenuto					Vincenzo	
					Carotenuto-	
					DIETI,	
					UniNA	
Submission of the	Researc		9	01/03/202		
conference paper "3D	h			1 -		
Localization for				30/04/202		
Multiplatform Radar				1		
Networks with						
Deployable Nodes" to						
the Signal Processing						
Symposium SPSympo- 2021.						
Journal submission of						
the paper A. Aubry, P.						
Braca, A. De Maio, and						
A. Marino "Enhanced						
	i .	•	1	1	1	i I

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Target Localization with Deployable Multiplatform Radar Nodes Based on Non- Convex Constrained Least Square Optimization" to the IEEE Transactions on Signal Processing. Matrix Analysis for Signal Processing with MATLAB- Augusto Aubry, Antonio De Maio Dr. Vincenzo Carotenuto	Courses		2		Profs. Augusto Aubry, Antonio De Maio Dr. Vincenzo Carotenuto- DIETI, UniNA	Y
Advanced Topics in Radar Signal Processing, dr. Alfonso Farina	Semina r	8	1.6	18-19-25- 26/05/202 1	Profs. Augusto Aubry, Antonio De Maio Dr. Vincenzo Carotenuto- DIETI, UniNA	Y
Revision of the conference paper "3D Localization for Multiplatform Radar Networks with Deployable Nodes", accepted for publication at the Signal Processing Symposium SPSympo-2021. Research activity regarding multitarget tracking algorithms for multiplatform radar systems.	Researc h	7		01/05/202 1 - 30/06/202 1		
Submission of the conference paper "Constrained Target Localization for Multiplatform Radar Systems" to the Military Communications Conference MILCOM	Researc h	6		01/07/202 1 - 31/08/202 1		

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2021. Study of: Kalman Filter, Extended Kalman Filter, Unscented Kalman Filter, Particle Filter, Nonmaneuver and Coordinate-Uncoupled Maneuver models (White-Noise Acceleration, Wiener-Process Acceleration, Singer and Mean-Adaptive Acceleration model).						
Teoria dell'Informazione, Prof. Marco Lops	Course	48	6	30/09/202 0 - 15/01/202 1 (exam on 08/10/202	Prof. Marco Lops- DIETI, UniNA	Y
Presentation of the	Researc		7	1) 01/09/202		
contribution "3D Localization for Multiplatform Radar Networks with Deployable Nodes" at the Young Scientist Contest of the Signal Processing Symposium: 1th classified. Work on algorithms regarding the research acitivity on multitarget tracking for multiplatform radar systems.	h			1 - 21/10/202 1		

¹⁾ Courses, Seminar, Doctoral School, Research, Tutorship

2.1. Study and training activities - credits earned

	Courses	Seminars	Research	Tutorship	Total
Bimonth 1	0	2.7	6	0	8.7
Bimonth 2	9	0.2	7	0	16.2
Bimonth 3	3	2.5	9	0	14.5
Bimonth 4	2	1.6	7	0	10.6
Bimonth 5	0	0	6	0	6
Bimonth 6	6	0	7	0	13

²⁾ Choose: Y or N

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Total	20	7	42	0	69
Expected	30 - 70	10 - 30	80 - 140	0 - 4.8	

3. Research activity:

Design of localization techniques in Multiplatform radar systems.

TOPIC

Multiplatform radar networks (MPRNs) allow to enlarge the surveillance area, to improve data reliability and accuracy, to enhance the fault tolerance, and to improve the data utilization of the system. As in multistatic systems, MPRN configuration can exploit spatial diversity, improving target detectability (in particular against low-observable and stealth targets) and endowing better resistance to electronic countermeasures, such as focused jamming. In addition, these surveillance infrastructures may boost their sensing capabilities via geometric diversity which refers to the possibility to optimize dynamically the number and the locations of the individual platforms. Hence, the use of low-cost receiving units, possibly expendable and heterogeneous, is of particular interest. Furthermore, small Unmanned Aerial Vehicles (UAVs) can be equipped with such simple receiver units, forming an intelligent network with enhanced performance and robustness.

The research carried out focused on a novel approach for 3D localization in multiplatform systems with a single transmitter and multiple receivers.

METHODOLOGY

Angular constraints are forced on the target position to capitalize on the information embedded into the characteristics of the active node radiation pattern, formulating the localization as a constrained Least Squares (LS) problem. The resulting non-convex optimization problem is efficiently handled invoking the Karush-Kuhn-Tucker (KKT) optimality conditions. The determination of the optimal solution of the aforementioned problem is handled with the design of a smart rooting method based on bisection algorithm in order to determine all the solutions of non-linear equations.

RESULTS

A novel 3D target localization strategy for Cooperating Radio Frequency sensor Nodes (C-RFNs), composed of a master transmit-receive node and multiple receive sensors, is derived. The overall target localization process demands a computational complexity proportional to the squared number of receive units, since the solution is determined in quasi-closed-form. The performance of the proposed algorithm is analyzed in terms of Root Mean Square Error (RMSE), proving that the devised technique achieves a significant accuracy gain over the counterparts, especially for weak target returns.

Possible future research includes:

- Experimental validation of the proposed algorithm on measured data;
- Extension of the developed framework to a C-RFN comprising multiple transmitters;
- Cognitive approach to optimally compute the UAV-receivers' trajectories to enhance the overall performance and optimally react to environmental changes or to the target trajectories.

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4. Research products

[J1] A. Aubry, P. Braca, A. De Maio, and A. Marino, "2D PBR Complying with Constraints Forced by Active Radar Measurements", IEEE Transactions on Aerospace & Electronic Systems, IEEE TAES, Published, 2021.

[J2] A. Aubry, P. Braca, A. De Maio, A. Marino, "Enhanced Target Localization with Deployable Multiplatform Radar Nodes Based on Non-Convex Constrained Least Squares Optimization", IEEE Transactions on Signal Processing, IEEE TSP, Under revision (RQ), 2021.

[C1] A. Marino, A. Aubry, A. De Maio, and P. Braca, "3D Localization for Multiplatform Radar Networks with Deployable Nodes", Signal Processing Symposium, Published, 2021.

[C2] A. Marino, A. Aubry, A. De Maio, P. Braca, and D. Gaglione, "Constrained Target Localization for Multiplatform Radar Systems", Military Communications Conference MILCOM 2021, Accepted, 2021.

5. Conferences and seminars attended

- Student Contest of the 1st International Virtual School on Radar Signal Processing University of Electronic Science and Technology of China (UESTC), 22-23 December 2020. 1 paper presented. Ranked Third to the Student Contest.
- Signal Processing Symposium (SPSympo) 2021, 21-23 September 2020, Lodz, Poland. 1 paper presented. Received the Young Scientist Contest Award (First Prize).

6. Periods abroad and/or in international research institutions

01.07.2021 – **present**

Centre for Maritime Research & Experimentation NATO, La Spezia Supervisor: Dr. Paolo Braca.

I have studied several filtering algorithms such as Kalman Filter, Extended Kalman Filter, Unscented Kalman Filter, Particle Filter, and different target motion models, i.e., Nonmaneuver and Coordinate-Uncoupled Maneuver models (White-Noise Acceleration, Wiener-Process Acceleration, Study of Singer and Mean-Adaptive Acceleration model). I have continued the study of localization problem for multiplatform radar systems, developing and testing different algorithms.

I have currently spent four months abroad in the current year.

7. Tutorship

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8. Plan for year three

For the third year of the PhD course, the plan is to continue the research activities focused on localization and tracking for multiplatform radar systems, possibly considering the case of multiple transmitters. Furthermore, the design of tracking algorithms exploiting angular constraints resulting from the characteristics of the radiation pattern will be investigated. If possible, the devised algorithms will be tested on real data.

Three months from February 2022 to April 2022 will be spent in Netherlands Organisation for Applied Scientific Research (TNO), Delft, Netherlands, where the tutor will be Dr Laura Anitori. The research activities will focus on the acquisition of measurements from real sensors and the consequent testing of the developed localization and tracking algorithms.

Finally, the title of the thesis will be "Advanced Target Localization Strategies for Multiplatform Systems via Constrained Optimization."

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