

UNIVERSITÀ DEGLI STUDI DI NAPOLI FEDERICO II





PHD STUDENT FABRIZIO TAVANO

TOPIC 1: DEVELOPMENT OF CONVOLUTIONAL NEURAL NETWORK AND FINGERPRINTING SYSTEM FOR AUTOMATED RAILWAY DAMAGE DETECTION USING MAGNETIC FLUX LEAKAGE TECHNOLOGY

TOPIC 2: DEVELOPMENT OF AN EFFICIENT STRATEGY TO LEAD A TEAM OF ROBOT WORKING FOR THE SANIFICATION OF THE RAILWAY STATIONS

TUTOR: PROF LIPPIELLO VINCENZO

CYCLE: XXXV

YEAR: 2020

MY BACKGROUND

- PhD student: Fabrizio Tavano
- DR number: DR993890
- Date of birth: 29/08/1981
- Master Science degree: Electronic Engineering University of Naples
- Doctoral Cycle: XXXV
- Scholarship type: no scholarship
- Tutor: Prof. Lippiello Vincenzo





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DEVELOPMENT OF AN EFFICIENT STRATEGY TO LEAD A TEAM OF ROBOT WORKING FOR THE DISINFECTION OF THE RAILWAY STATIONS

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DEVELOPMENT OF CONVOLUTIONAL NEURAL NETWORK AND FINGERPRINTING SYSTEM FOR AUTOMATED RAILWAY DAMAGE DETECTION USING MAGNETIC FLUX LEAKAGE TECHNOLOGY

Image not available because the prototype in phase of patenting



electrical engineering



FIRST PUBLICATION ABOUT THIS STUDY

in Preparation:

Authors: Fabrizio Tavano & Alessandro Paolo Daga, Luigi Garibaldi, Aldo Canova, Alessandro Fasana, Vincenzo Lippiello, Bruno Siciliano, Riccardo Caccavale, Eugenio Fedeli, Vincenzo Calà, Mirko Ermini, Marcella Di Mario, Francesco Giuliano, Franco Stivali, Riccardo Santoro, Fiorella Fedele, (2020).

Title: Development of Convolutional Neural Network and fingerprinting system for automated railway damage detection using Magnetic flux leakage technology.

In process of submission to the journal: IET Electrical Systems in Transportation-.

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Image not available because the prototype in phase of patenting

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SUMMARY OF STUDY ACTIVITIES IN THIS YEAR

Module	Professor		
Safety critical System for railway	Mario		
traffic management	Barbareschi		
Robotic interaction control	Prof. Siciliano		
Field and service robotics,	Prof.Ruggiero		
Machine learning	Prof. Sansone		
Mathematics of the Finite Element			
Method	Prof.Calabrò		
Robotic lab	Prof. Lippiello		
Artificial Intelligence	Prof.ssa Amato		

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Seminars/Workshop	Organizer		
Numerical methods for	Prof. Dr. Fanny		
modelling, simulation and	Ficuciello		
control for softrobots or robots			
in interaction with deformable			
environment			
Cybersecurity and Fuzzing for	Dr. Roberta		
robots, blochchain, and more	Natella		
"Large Scale Training of Deep	Prof. Carlo		
Neural Networks	Sansone		
Exploring Autonomy in Robotic	Prof. Dr. Fanny		
Flexible Endoscopy,	Ficuciello		
"Wearable Brain-Computer	Prof. Pasquale		
Interface for Augmented	Arpaia;		
Reality-based Robotic			
Applications in Industry 4.0"			
	NVIDIA, CINI		
Al Webinar Series on Deep	National Lab,		
Learning	CINECA		

STUDY AND TRAINING ACTIVITIES - CREDITS EARNED

	Courses	Seminar	Research	Tutorship	Total
		S			
Bimonth 1	0	2.4	7	0	9.4
Bimonth 2	3.3	0.4	10	0	13.7
Bimonth 3	0	0.8	10	0	10.8
Bimonth 4	29	3.6	10	0	42.6
Bimonth 5	3.6	1	10	0	14.6
Bimonth 6	8.6	2.8	10	0	21.4
Total	44.5	11	57	0	112.5
Expected	30 - 70	10 - 30	80 - 140	0 - 4.8	

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STUDY ACTIVITIES IN THE NEXT YEAR

Module	Professor
Statistical Machine Learning	Prof.ssa Corazza
Human-Robot Interaction	Prof.ssa Rossi
Robotics Fundations	Prof. Siciliano
Intelligent Robotics	Prof. Finzi
Neural Networks and Machine Learning	Prof. Prevete

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